

5.2 Global one-dimensional branches

The following gives a global extension of (Δ, κ) from $(0, \varepsilon)$ to $(0, \infty)$ in the $\mathbb{R}$ -analytic case.

Theorem 5.2.1 Suppose (G1)-(G3) hold, $\Delta' \neq 0$ on $(-\varepsilon, \varepsilon)$ and in $\mathbb{R} \times X$ all bounded closed subsets of $\mathcal{S}$ are compact.

Then there exists a continuous curve $\mathcal{R}$ which extends $\mathcal{R}^+$ such that

(a) $\mathcal{R} = \{(\Delta(s), \kappa(s)) : s \in [0, \infty)\} \subset U$, where $(\Delta, \kappa) : [0, \infty) \rightarrow \mathbb{R} \times X$ is conts.

(b) $\mathcal{R}^+ \subset \mathcal{R} \subset \mathcal{S}$.

(c) The set $\{s \geq 0 : \ker(\partial_x F[\Delta(s), \kappa(s)]) \neq \{0\}\}$ has no accumulation points.

(d) At each point, $\mathcal{R}$ has a local analytic re-parametrization:

(d1) at right nbhd of 0, $\mathcal{R}$ coincides with $\mathcal{R}^+$;

(d2) for $s^* \in (0, \infty)$, $\exists p^* : (-1, 1) \rightarrow \mathbb{R}$ injective, continuous s.t.

$p^*(0) = s^*$, $t \mapsto (\Delta(p^*(t)), \kappa(p^*(t)))$ is analytic, for $t \in (-1, 1)$.
 only injective on $[s^*, s^* + \varepsilon^*]$
 NOT on $[s^* - \varepsilon^*, s^* + \varepsilon^*]$

local injective p^* moreover, $\exists \varepsilon^* > 0$ s.t. $t \mapsto \Delta(p^*(t))$ is injective on $[s^*, s^* + \varepsilon^*]$ and on $[s^* - \varepsilon^*, s^*]$.

(e) One of the following occurs:

(i) $\|(\Delta(s), \kappa(s))\| \rightarrow \infty$ as $s \rightarrow \infty$

(ii) $(\Delta(s), \kappa(s))$ approaches to ∂U as $s \rightarrow \infty$

(iii) $\mathcal{R}$ is a closed loop, i.e. $\exists T > 0$ s.t.

$$\mathcal{R} = \{(\Delta(s), \kappa(s)) : 0 \leq s \leq T\}, \text{ with } \Delta(0) = \lambda_0, \kappa(0) = 0.$$

We may assume T is the smallest such number and

$$(\Delta(s+T), \kappa(s+T)) = (\Delta(s), \kappa(s)) \quad \forall s \geq 0$$

H.

(f) If for some $s_1 \neq s_2$,

$$(\Delta(s_1), \kappa(s_1)) = (\Delta(s_2), \kappa(s_2)) \text{ where } \ker \partial_x F[\Delta(s_1), \kappa(s_1)] = \{0\},$$

then (e)(iii) occurs and $|s_1 - s_2|$ is an integer multiple of T .

(In particular, $(\Delta, \kappa): [0, \infty) \rightarrow \mathcal{S}$ is locally injective.)

Remark 5.2.2

- $\mathcal{R}$ need not to be a maximal connected subset of $\mathcal{S}$, other curves or manifolds of $\mathcal{S}$ may intersect $\mathcal{R}$.
- $\mathcal{R}$ is locally injective, but may not be globally injective.
- $\mathcal{R}$ may have self-intersecting points.
- $\mathcal{R}$ may not be a smooth curve, but for ε^* sufficiently small, the two segments of $\{(\Delta(s), \kappa(s)) : 0 < |s - s^*| < \varepsilon^*\}$ (with $(\Delta(s^*), \kappa(s^*))$ removed) are smooth curves which can be parametrized by λ .

Br 5.2.1 The proof will be divided in several steps.

$$\text{Let } \mathcal{N} := \{(\lambda, x) \in \mathcal{S} : \ker \partial_x F[\lambda, x] = \{0\}\}$$

— the set of nonsingular solutions of $F(\lambda, x) = 0$ in $\mathcal{U}$.

[for $(\lambda, x) \in \mathcal{N}$, by (G2), $\dim \ker \partial_x F[\lambda, x] = \text{codim range } \partial_x F[\lambda, x] = 0$

$\Rightarrow \partial_x F[\lambda, x]: X \rightarrow Y$ is bijective (and of course continuous)

$\Rightarrow \partial_x F[\lambda, x]: X \rightarrow Y$ is a homeomorphism $\xrightarrow{\text{I.F.T.}} \exists \lambda \in I \subset \mathbb{R}$ and $g: I \rightarrow X$ s.t.
locally around $(\lambda, x) = \{(\lambda, g(\lambda)) : \lambda \in I\}$
in $\mathcal{S}$

$$\left. \begin{array}{l} \Lambda' \neq 0 \text{ on } (-\varepsilon, \varepsilon) \\ \Lambda \text{ is } \mathbb{R}\text{-analytic} \end{array} \right\} \Rightarrow \Lambda'(s) \neq 0 \quad \forall s \in (-\varepsilon, \varepsilon) \setminus \{s_0\} \text{ for } \varepsilon \text{ small.}$$

$$\xrightarrow[4.3.4(b)]{\text{Prop}} \mathcal{R}^+ \subset \mathcal{N} \text{ for } \varepsilon \text{ small.}$$

Def. 5.2.3 A distinguished arc is a maximal connected subset of $\mathcal{N}$.

For a distinguished arc $\mathcal{L}$ of $\mathcal{N}$, by I.F.T., and (G2),

$\exists$ a (possibly infinite) open interval $I \subset \mathbb{R}$, an $\mathbb{R}$ -analytic $g: I \rightarrow X$ s.t.

$$\mathcal{L} = \{(\lambda, g(\lambda)) : \lambda \in I\}.$$

Step 1 (L-S reduction) Since structure around points of $\mathcal{N}$ is clear, we consider points of $\mathcal{S} \setminus \mathcal{N}$, to which we want to apply the structure theorem of analytic varieties.

Let $(\lambda_*, x_*) \in \mathcal{S} \setminus \mathcal{N}$. Using Theorem 4.2.1 (L-S red.),

$\exists_{(\lambda_*, 0) \in V} V \subset \mathbb{R} \times \ker \partial_x F[\lambda_*, x_*]$, $\psi: V \rightarrow X$ $\mathbb{R}$ -analytic, and $\mathbb{R}$ -analytic $h: V \rightarrow \mathbb{R}^q$ for $q = \dim \ker \partial_x F[\lambda_*, x_*]$ such that

(a) $\psi(\lambda_*, 0) = x_*$, $(\lambda, \psi(\lambda, \xi)) \in U$, $\forall (\lambda, \xi) \in V$

(b) $h(\lambda, \xi) = 0 \Leftrightarrow F(\lambda, \psi(\lambda, \xi)) = 0 \quad \forall (\lambda, \xi) \in V$

(c) $\forall (\lambda, x) \in U$ with $F(\lambda, x) = 0$ and $|(\lambda, x) - (\lambda_*, x_*)|$ small, we have

$$\exists \xi \in \ker \partial_x F[\lambda_*, x_*] \text{ s.t. } (\lambda, \xi) \in V \text{ and } x = \psi(\lambda, \xi).$$

(d) $\dim \ker \partial_x F[\lambda, \psi(\lambda, \xi)] = \dim \ker \partial_\xi h(\lambda, \xi) \quad \forall (\lambda, \xi) \in V.$

Note that $h: V \subset \mathbb{R}^{\times} \ker \partial_x F[\lambda_*, x_*] \simeq \mathbb{R} \times \mathbb{R}^g \rightarrow \mathbb{R}^g$ is $\mathbb{R}$ -analytic,

by considering its g components: $h = (h_1, h_2, \dots, h_g)$ (each of these components is $\mathbb{R}$ -analytic). Define

$$A = \text{var}(V, \{h_1, h_2, \dots, h_g\}) = \{(\lambda, \xi) \in V : h(\lambda, \xi) = 0\}$$

— an $\mathbb{R}$ -analytic variety in V

$$M = \{(\lambda, \xi) \in V : (\lambda, \psi(\lambda, \xi)) \in \mathcal{N}\}$$

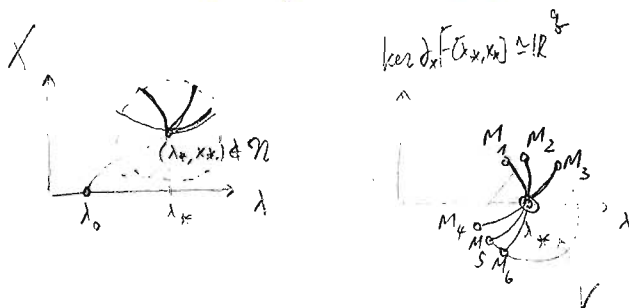
— an $\mathbb{R}$ -manifold in V (of dimension 1.)

$$\begin{aligned} \uparrow (\lambda, \psi(\lambda, \xi)) \in \mathcal{N} &\Rightarrow 0 = \dim \ker \partial_x F[\lambda, \psi(\lambda, \xi)] = \dim \ker \partial_\xi h[\lambda, \xi] \Rightarrow \partial_\xi h[\lambda, \xi] \text{ is an isom.} \\ &\Rightarrow \text{locally around } (\lambda, \xi) \text{ in } M, M \text{ is a 1-dim. curve passing through } (\lambda, \xi). \end{aligned}$$

Thus, M is composed of 1-regular points of A .

Write $\{M_j : j \in J\}$ for the set of non-empty connected components of M .

We assume that $(\lambda_*, 0) \in \overline{M_j}$, $\forall j \in J$
(otherwise, we choose V smaller.)



Complexification of V, h, A, M : (to use the structure theorem)

$$h: V \subset \mathbb{R}^{g+1} \rightarrow \mathbb{R}^g$$

$$(x_1, x_2, \dots, x_{g+1}) \mapsto (h_1(x_1, \dots, x_{g+1}), \dots, h_g(x_1, \dots, x_{g+1}))$$

$$h: V \subset \mathbb{C}^{g+1} \rightarrow \mathbb{C}^g$$

$$(z_1, z_2, \dots, z_{g+1}) \mapsto (h_1(z_1, \dots, z_{g+1}), \dots, h_g(z_1, \dots, z_{g+1}))$$

where every $h_i = h_i(x_1, \dots, x_{g+1})$ is its Taylor series, a sum of polynomials:

$$a \cdot x_1^{n_1} x_2^{n_2} \dots x_{g+1}^{n_{g+1}}$$

replacing $x_{\mathbb{R}}$ with $z_{\mathbb{C}}$

$$a \cdot z_1^{n_1} z_2^{n_2} \dots z_{g+1}^{n_{g+1}}$$

$$A^c := \{ (\lambda, \xi) \in V^c : h^c(\lambda, \xi) = 0 \} \quad \leftarrow \text{complexification of } A, M.$$

$$M^c := \{ (\lambda, \xi) \in V^c : \ker d_\xi h^c(\lambda, \xi) = \{0\} \}$$

Write $\{\hat{M}_i : i \in I\}$ for the set of non-empty connected components of M^c .

↑ disconnected sets after complexification may become connected ↓

Clearly, for every M_j , there is an $i \in I$ such that $M_j \subset \hat{M}_i$.

Step 2 (Application of the structure theorem)

Applying Theorem 5.1.5 on A^c , by (a)(b),

$$\gamma_{(\lambda_*, 0)}(A^c) = \gamma_{(\lambda_*, 0)}(B_1 \cup \dots \cup B_N \cup \{(\lambda_*, 0)\}),$$

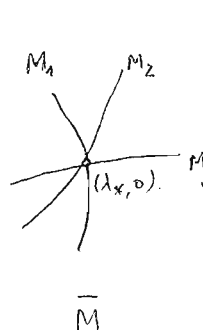
where every B_k is a connected $\mathbb{C}$ -analytic manifold of some dimension m_k .

By (d)(e) for every $i \in I$, there is a (real-on-real) branch B_i s.t.

$$\gamma_{(\lambda_*, 0)}(\hat{M}_i) \subset \gamma_{(\lambda_*, 0)}(\bar{B}_i), \text{ and } \dim_{\mathbb{C}} B_i = 1, B_i \subset A^c.$$

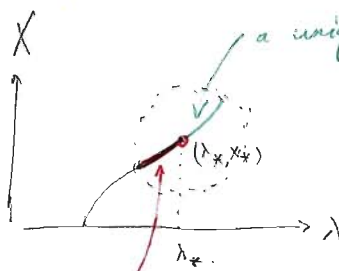
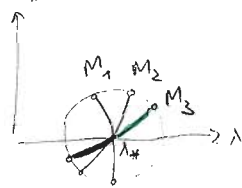
By making V^c smaller if necessary, we can assume

$$B_i \setminus \{(\lambda_*, 0)\} \subset \hat{M}_i.$$

Returning to $\mathbb{R}$ -setting, we have $\bar{M}$ is locally around $(\lambda_*, 0)$,

a union of finitely many $\mathbb{R}$ -analytic curves which pass through $(\lambda_*, 0)$ in V and intersect each other **only** at $(\lambda_*, 0)$.

Lifting this conclusion to infinite dimensional $\mathbb{R} \times X$:

$$\ker d_x [F(\lambda_*, x_*)] \cong \mathbb{R}^q$$



a unique extension of L beyond (λ_*, x_*)
(given by M_3).

lies in some distinguished arc L

Def. 5.2.4 A route of length $N \in \mathbb{N} \cup \{\infty\}$ is a set

$\{A_n : 0 \leq n < N\}$ of distinguished arcs and a set

$\{(\lambda_n, x_n) : 0 \leq n < N\} \subset \mathbb{R} \times X$ such that

(a) $(\lambda_0, x_0) = (\lambda_0, 0)$ is the bifurcation point;

(b) $\mathbb{R}^+ \subset A_0$;

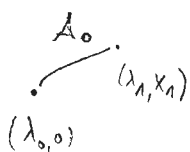
(c) $(\lambda_{n+1}, x_{n+1}) \in (\partial A_n \cap \partial A_{n+1}) \setminus \{(\lambda_n, x_n)\}$ for $0 \leq n < N-1$, and

$\exists$ injective $\mathbb{R}$ -analytic $p : (-1, 1) \rightarrow A_n \cup A_{n+1} \cup \{(\lambda_{n+1}, x_{n+1})\}$ with $p(0) = (\lambda_{n+1}, x_{n+1})$

So A_{n+1} is uniquely determined by A_n by analyticity of p . $\square$

(d) $n \mapsto A_n$ is injective.

Step 3 (Existence of a maximal route)



I.F.T. $\Rightarrow$ existence of A_0 from $(\lambda_0, 0)$, whose other end point is denoted by (λ_1, x_1)

1-dim (by local theory)

A_0 uniquely determines A_1 uniquely $A_2 \dots$

existence $\checkmark$

Denote this max. route (extended from A_0) by

$\{(A_n, (\lambda_n, x_n)) : 0 \leq n < N\}$

Step 4: (Parametrization of a max. route)

Since every distinguished arc A_n can be parametrized by an $\mathbb{R}$ -analytic function, say $(\Lambda_n, \kappa_n) : (n, n+1) \rightarrow X$ s.t.

$$A_n = \{(\Lambda_n(s), \kappa_n(s)) : n < s < n+1\}$$

and every "joint" $(\Lambda_{n+1}, \kappa_{n+1})$ of A_n and A_{n+1} , the parametrization of A_n can be analytically extended to A_{n+1} (because locally around $(\Lambda_{n+1}, \kappa_{n+1})$, there is an analytic curve structure).

So there is the desired parametrization of

$$\mathcal{R} := \bigcup_{0 \leq n < \infty} (A_n \cup \{(\Lambda_n, \kappa_n)\}) \subset \overline{\mathcal{U}}$$



(a)(b)(c)(d)

(e) = We distinguish 3 cases:

- (1) $N = \infty$
 - (2) $N < \infty$ and $\overline{A_{N-1}}$ is not compact subset of U
 - (3) $N < \infty$ and $\overline{A_{N-1}}$ is compact subset of U
- } (i) or (ii) occurs
} (iii) occurs

Assume neither (i) nor (ii) happens, then

$\exists \{t_k\}_{k=1}^{\infty}$ with $t_k \rightarrow N$ s.t. $\{\Lambda(t_k), \kappa(t_k)\}$ is bounded in $\mathbb{R} \times X$
and bounded away from ∂U .

$\xrightarrow[\text{of S.2.1}]{\text{compactness assumption}}$

$\{\Lambda(t_k), \kappa(t_k)\}$ is rel. compact, say $(\Lambda(t_k), \kappa(t_k)) \rightarrow (\lambda^*, \kappa^*) \in \mathcal{S}$

If $N = \infty$, then every nbhd of $(1^*, x^*)$ intersect infinitely many distinct distinguished arcs. $\hookrightarrow$

in a nbhd of $(1^*, x^*)$,

the solution set is an analytic variety.

If $N < \infty$ and $\bar{A}_{N-1}$ is not compact in U , then (since $t_k \rightarrow \infty$)

$$A_{N-1} \cdot \begin{matrix} (1^*, x^*) \\ (x_{N-1}, x_{N-1}) \end{matrix} \quad (1^*, x^*) \in \partial A_{N-1} \setminus \{(x_{N-1}, x_{N-1})\},$$

thus the route can be extended beyond $(1^*, x^*)$ $\hookrightarrow$

max. route.

$\square$

in cases (1), (2),

either (i) or (ii) occurs.

For the case (3), if $N < \infty$ and $\bar{A}_{N-1}$ is compact in U ,

let (x_{N-1}, x_{N-1}) and (x_N, x_N) be the end points of A_{N-1} ,

since the route around (x_N, x_N) can be extended

further and the route is already maximal,

Def 5.2.4.

$$\stackrel{(d)}{\Rightarrow} A_N = A_m \text{ for some } m \in \{0, 1, \dots, N-2\}$$

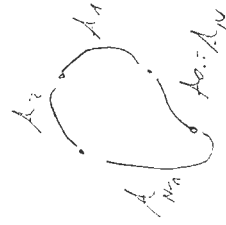
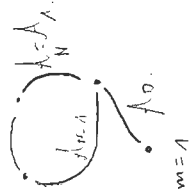
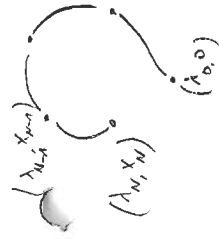
We show: $m = 0$.

If $m \in \{1, \dots, N-2\}$, then A_{N-1} is extension of $A_m = A_m$ (resp. A_{m+1})

but A_{m-1} is also extension of A_m ,

$$\Rightarrow A_{N-1} = A_{m-1} \text{ or } A_{m+1} \quad \hookrightarrow \text{Def. 5.2.4. (d)} \quad \square_{m=0}.$$

Thus, $A_0, \dots, A_N$ form a closed loop, (e)(iii) occurs $\square(e)$.



6f): If there are $s_1 \neq s_2$ with

$$(\Delta(s_1), \kappa(s_1)) = (\Delta(s_2), \kappa(s_2)) \text{ and } \ker \partial_x \bar{F}[\Delta(s_1), \kappa(s_1)] = \{0\}$$

then $(\Delta(s_1), \kappa(s_1)) \in A_{n_1}$ and $(\Delta(s_2), \kappa(s_2)) \in A_{n_2}$ for some $0 \leq n_1, n_2 < N$

I.F.T.

$\Rightarrow A_{n_1}, A_{n_2}$ coincide in a nbhd of $(\Delta(s_1), \kappa(s_1)) = (\Delta(s_2), \kappa(s_2))$

$\Rightarrow A_{n_1} = A_{n_2} \Rightarrow (e)(iii)$ occurs and $|s_2 - s_1|$ is a multiple of T .

$\square$
5.2.1.